

Proving Reachability Properties by Coinduction ¹

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- 1 Motivation
- 2 Induction and Coinduction
 - Motivation
 - Theoretical Foundation
 - (Co)Inductive Sets Defined by Ground Inference Systems
- 3 Reachability Predicates
- 4 Logical Constrained Rewriting Systems (LCTRSs)
- 5 A Coinductive Proof System for Reachability Formulas
- 6 Conclusion

Plan

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A Specification of a Transition System

$\langle n \rangle \rightarrow \langle n, a \rangle$ if $\exists y. y = a \wedge 2 \leq y \wedge y < n$

$\langle n, a \rangle \rightarrow \langle \text{composite} \rangle$ if $\text{isEulerWitness}(a, n)$

$\langle n, a \rangle \rightarrow \langle n \rangle$ if $\neg \text{isEulerWitness}(a, n)$

where

$\text{isEulerWitness}(a, n) \equiv ((a | n) = 0 \vee (a^{\frac{n-1}{2}} \neq a | n \pmod{n}))$

$a | n$ is the Jacobi symbol

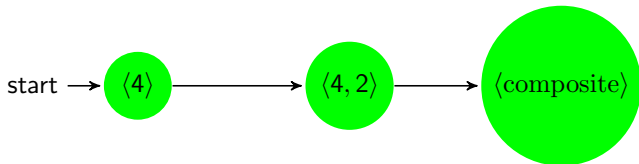
We want to show that

"if $\langle n \rangle$ goes to $\langle \text{composite} \rangle$ then

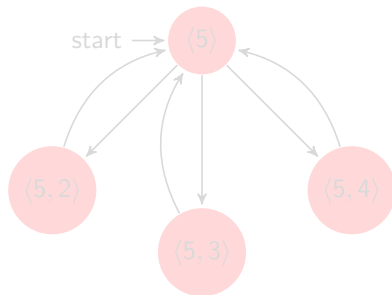
$\exists n_1, n_2. n = n_1 \cdot n_2 \wedge n_1 > 1 \wedge n_2 > 1$ ".

The First Issue

The computations can be finite:

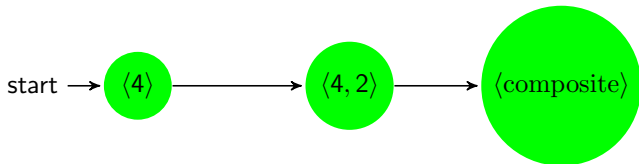


or infinite:

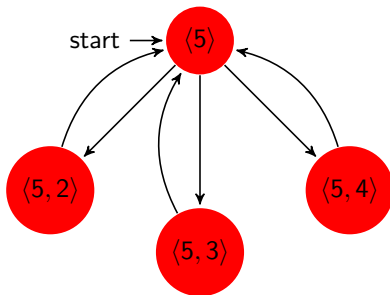


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The computations can be finite:



or infinite:



The Second Issue

The conditions

$$\exists y . y = a \wedge 2 \leq y \wedge y < n$$

$$((a \mid n) = 0 \vee (a^{\frac{n-1}{2}} \neq a \mid n \pmod{n}))$$

$$((a \mid n) = 0 \vee (a^{\frac{n-1}{2}} \neq a \mid n \pmod{n})) \rightarrow \exists n_1, n_2 . n = n_1 \cdot n_2 \wedge n_1 > 1 \wedge n_2 > 1$$

are very **complex first order formulas including functions and predicates** whose definitions are orthogonal with that of the transition system.

Our Proposal

- we use **coinduction** in order to handle both finite and infinite computations
- we introduce LCTRSs (Logical Constrained Term Rewriting Systems) for specifying transition systems
- we propose an effective **proof system** that, given a LCTRS, proves valid **reachability formulas**, assuming an oracle (e.g., an SMT solver) that solves logical constraints

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A Simpler Transition System Specification

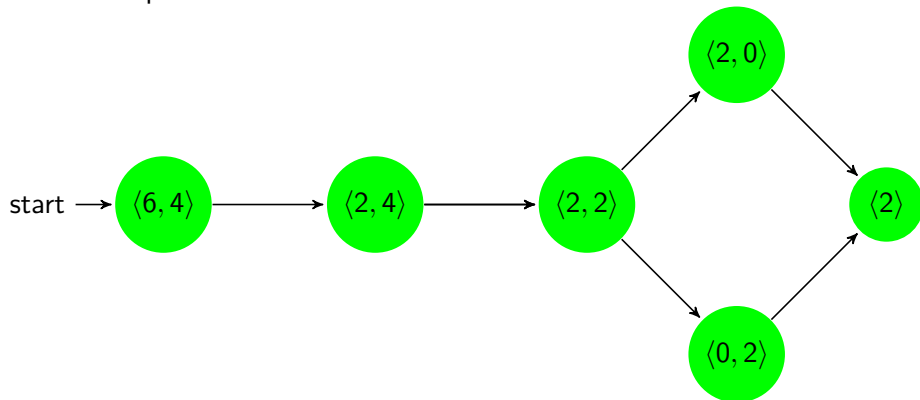
$$\langle a, b \rangle \rightarrow \langle a - b, b \rangle \text{ if } a \geq b$$

$$\langle a, b \rangle \rightarrow \langle a, b - a \rangle \text{ if } b \geq a$$

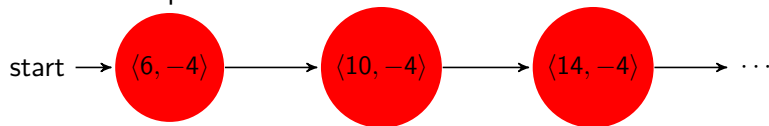
$$\langle a, b \rangle \rightarrow \langle a + b \rangle \quad \text{if } a = 0 \vee b = 0$$

Two Computations

– finite computations



– infinite computations



A Possible Specification of Computations

- using BNF notation:

$$C ::= \langle a \rangle \mid \langle a, b \rangle \rightsquigarrow C$$

- equivalently, using inference rules

$$\frac{}{\langle a \rangle} \quad \frac{C}{\langle a, b \rangle \rightsquigarrow C}$$

Question

- Are these specifications appropriate?
- I.e., do they uniquely define the computations?

Answer

Yes, if

- we consider the **smallest fixed-point** satisfying the rules (finite computations, **inductively defined**), or
- we consider the **greatest fixed-point** satisfying the rules (finite computations + infinite computations, **coinductively defined**)

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Complete Lattices

- **partial ordered set (poset)**: set L together with a binary relation $\sqsubseteq \subseteq L \times L$ that is
 - ▶ reflexive
 - ▶ transitive
 - ▶ antisymmetric
- **complete lattice** = a poset with all **lubs** (least upper bounds, **joins**), and hence also all **glbs** (greatest lower bounds, **meets**)
- notations:
 - ▶ lub of x and y : $x \sqcup y$
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- the most known (and used) example: $(\mathcal{P}(X), \subseteq)$, where X is a set

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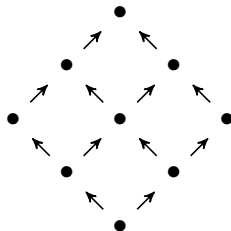
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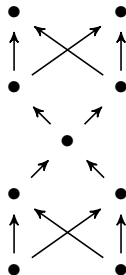
Examples of Lattices

y
↑
 x



$x \sqsubset y$

complete lattice



poset that is not
a complete lattice

Fixed Points

Let (L, \sqsubseteq) be a complete lattice and $f : L \rightarrow L$.

- $x \in L$ **pre-fixed point** of f if $f(x) \sqsubseteq x$
- $x \in L$ **post-fixed point** of f if $x \sqsubseteq f(x)$
- $x \in L$ **fixed point** of f if $f(x) = x$

Terminology:

- pre-fixed point, f -forward-closed, f -closed
- post-fixed point, f -backward-closed, f -stable, f -consistent

Knaster-Tarski Theorem 1/2

Let (L, \sqsubseteq) be a complete lattice.

$f : L \rightarrow L$ is **monotone** if $f(x) \sqsubseteq f(y)$ whenever $x \sqsubseteq y$.

Theorem (Knaster-Tarski)

Any $f : L \rightarrow L$ monotone has

- a **least fixed point** $\mu y. f(y)$ (on short μf), and
- a **greatest fixed point** $\nu y. f(y)$ (on short νf).

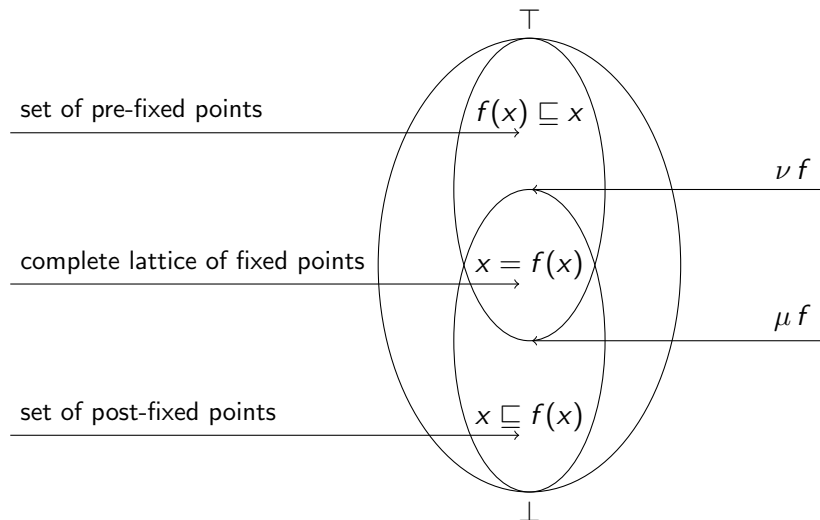
Moreover,

- $\mu f = \bigsqcap \{x \mid f(x) \sqsubseteq x\}$ and
- $\nu f = \bigsqcup \{x \mid x \sqsubseteq f(x)\}$

i.e.,

- μf is **the meet of pre-fixed points**
- νf is **the join of post-fixed point**

Knaster-Tarski Theorem 2/2



(Co)Induction Proof Principle

$f : L \rightarrow L$ monotone

- induction proof principle:

$$\frac{f(x) \sqsubseteq x}{\mu f \sqsubseteq x} \mu\text{-rule}$$

- coinduction proof principle:

$$\frac{x \sqsubseteq f(x)}{x \sqsubseteq \nu f} \nu\text{-rule}$$

(Co)Continuous Functions and Kleene Theorem

$f : L \rightarrow L$ is **continuous** if $f(\bigsqcup_{n \geq 0} x_n) = \bigsqcup_{n \geq 0} f(x_n)$ for any increasing chain $x_0 \sqsubseteq x_1 \sqsubseteq \dots$.

$f : L \rightarrow L$ is **cocontinuous** if $f(\prod_{n \geq 0} x_n) = \prod_{n \geq 0} f(x_n)$ for any decreasing chain $x_0 \supseteq x_1 \supseteq \dots$.

Theorem (Kleene)

If $f : L \rightarrow L$ is continuous then $\mu f = \bigsqcup_{n \geq 0} f^n(\perp)$.

If $f : L \rightarrow L$ is cocontinuous then $\nu f = \prod_{n \geq 0} f^n(\top)$.

The theorem supplies a practical way to compute the least/greatest fixed points, or their approximations.

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Inductive and Coinductive Set Definitions

Context:

- U an universe set
- $(L, \sqsubseteq) = (\mathcal{P}(U), \subseteq)$
- $\perp = \emptyset, \top = U$
- $\bigsqcup \mathcal{X} = \bigcup \langle X \mid X \in \mathcal{X} \rangle,$
- $\bigsqcap \mathcal{X} = \bigcap \langle X \mid X \in \mathcal{X} \rangle,$ where $\mathcal{X} \subseteq \mathcal{P}(U)$

Definition

A set $X \subseteq U$ is **inductively defined** if there is f monotone s.t. $X = \mu f$.

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Ground (Inference) Systems

[source: David Sangiorgi, 2008 (Chap. 2 in the book Introduction to Bisimulation and Coinduction, 2012)]

Definition

Let U be a set. A **ground (inference) rule** on U is a pair (S, x) , where $S \subseteq U$, $x \in U$.

S is called the **premise** of the rule and x the **conclusion** of the rule.

If $S = \{x_1, x_2, \dots\}$, then a rule (S, x) is written as

$$\frac{x_1, x_2, \dots}{x}$$

If $S = \emptyset$ then the rule is called **axiom**.

Functional of a Ground (Inference) System

Definition

A set \mathcal{R} of ground rules yields a function $\widehat{\mathcal{R}} : \mathcal{P}(U) \rightarrow \mathcal{P}(U)$ given by

$$\widehat{\mathcal{R}}(X) = \{x \mid (\exists S' \subseteq X)(S', x) \in \mathcal{R}\}.$$

Proposition

If \mathcal{R} is a set of ground rules, then $\widehat{\mathcal{R}}$ is monotone.

It follows that each set of ground rules \mathcal{R} inductively defines a set $\mu \widehat{\mathcal{R}}$ and coinductively defines a set $\nu \widehat{\mathcal{R}}$.

Functional of a Ground (Inference) System at Work

$$U = (\mathbb{Z} \cup \{\langle, \rangle, ", ", \sim\})^\infty$$

$$[A] \frac{}{\langle a \rangle} \quad a \in \mathbb{Z} \quad [B] \frac{\tau}{\langle a, b \rangle \sim \tau} \quad a, b \in \mathbb{Z}$$

$$\mathcal{R} = \{[A], [B]\}$$

$$X = \left\{ \begin{array}{l} \langle 2, 5 \rangle \sim \langle 5, 3 \rangle, \\ \sim \rangle 7, 2, 6 \langle, \\ \langle 1 \rangle \sim \langle 1 \rangle \sim \dots \end{array} \right\}$$

$$\widehat{\mathcal{R}}(X) = \{\langle a \rangle \mid a \in \mathbb{Z}\} \cup \left\{ \begin{array}{l} \langle a, b \rangle \sim \langle 2, 5 \rangle \sim \langle 5, 3 \rangle, \\ \langle a, b \rangle \sim \sim \rangle 7, 2, 6 \langle, \\ \langle a, b \rangle \sim \langle 1 \rangle \sim \langle 1 \rangle \sim \dots \end{array} \middle| a, b \in \mathbb{Z} \right\}$$

Functional of a Ground (Inference) System at Work

$$U = (\mathbb{Z} \cup \{\langle, \rangle, ", ", \sim\})^\infty$$

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Functional of a Ground (Inference) System at Work

$$U = (\mathbb{Z} \cup \{\langle, \rangle, ", ", \rightsquigarrow\})^\infty$$

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Induction Principle on Rules

if $\widehat{\mathcal{R}}(X) \subseteq X$ then $\mu(\widehat{\mathcal{R}}) \subseteq X$

that means that

for a given X ,

if for all rules $(S, x) \in R$, if $S \subseteq X$, then also $x \in X$

then $\mu(\widehat{\mathcal{R}}) \subseteq X$

Coinduction Principles on Rules

if $X \subseteq \widehat{\mathcal{R}}(X)$ then $X \subseteq \nu(\widehat{\mathcal{R}})$

that means that

for a given X ,

if for all $x \in X$ there is a rule $(S, x) \in R$ with $S \subseteq X$

then $X \subseteq \nu(\widehat{\mathcal{R}})$

Example

$$\langle a, b \rangle \rightarrow \langle a - b, b \rangle \text{ if } a \geq b$$

$$\langle a, b \rangle \rightarrow \langle a, b - a \rangle \text{ if } b \geq a$$

$$\langle a, b \rangle \rightarrow \langle a + b \rangle \quad \text{if } a = 0 \vee b = 0$$

$$U = (\mathbb{Z} \cup \{\langle, \rangle, ", ", \sim\})^\infty$$

$$[A] \frac{}{\langle a \rangle} a \in \mathbb{Z} \quad [B] \frac{\tau}{\langle a, b \rangle \sim \tau} \exists \text{ transition from } \langle a, b \rangle \text{ to } hd(\tau)$$

The set of **finite executions**: $C^+ = \mu \widehat{[A, B]}$

The set of **infinite and finite executions**: $C^\infty = \nu \widehat{[A, B]}$

The set of **infinite executions**: $C^\omega = \nu \widehat{[B]}$

Proof Trees

$$\begin{array}{c} [A] \frac{}{\langle 2 \rangle} \\ [B] \frac{\langle 2, 0 \rangle \rightsquigarrow \langle 2 \rangle}{\langle 2, 2 \rangle \rightsquigarrow \langle 2, 0 \rangle \rightsquigarrow \langle 2 \rangle} \\ [B] \frac{\langle 2, 2 \rangle \rightsquigarrow \langle 2, 0 \rangle \rightsquigarrow \langle 2 \rangle}{\langle 2, 4 \rangle \rightsquigarrow \langle 2, 2 \rangle \rightsquigarrow \langle 2, 0 \rangle \rightsquigarrow \langle 2 \rangle} \\ [B] \frac{\langle 2, 4 \rangle \rightsquigarrow \langle 2, 2 \rangle \rightsquigarrow \langle 2, 0 \rangle \rightsquigarrow \langle 2 \rangle}{\langle 6, 4 \rangle \rightsquigarrow \langle 2, 4 \rangle \rightsquigarrow \langle 2, 2 \rangle \rightsquigarrow \langle 2, 0 \rangle \rightsquigarrow \langle 2 \rangle} \end{array}$$

finite proof tree

$$\begin{array}{c} \dots \\ [B] \frac{\dots}{\langle 14, -4 \rangle \rightsquigarrow \langle 18, -4 \rangle \rightsquigarrow \langle 22, -4 \rangle \rightsquigarrow \dots} \\ [B] \frac{\langle 14, -4 \rangle \rightsquigarrow \langle 18, -4 \rangle \rightsquigarrow \langle 22, -4 \rangle \rightsquigarrow \dots}{\langle 10, -4 \rangle \rightsquigarrow \langle 14, -4 \rangle \rightsquigarrow \langle 18, -4 \rangle \rightsquigarrow \dots} \\ [B] \frac{\langle 10, -4 \rangle \rightsquigarrow \langle 14, -4 \rangle \rightsquigarrow \langle 18, -4 \rangle \rightsquigarrow \dots}{\langle 6, -4 \rangle \rightsquigarrow \langle 10, -4 \rangle \rightsquigarrow \langle 14, -4 \rangle \rightsquigarrow \dots} \end{array}$$

infinite proof tree

Proof Trees Supply Proofs

A tree is **well-founded** if the relation on the nodes, which contains a pair of nodes (n, p) if p is the parent of n , is well-founded.

Remark

Finite proof trees are well-founded.

Proposition

Let \mathcal{R} be a set of a set of ground rules over U such that \mathcal{R} is cocontinuous.

Then $x \in \mu \widehat{\mathcal{R}}$ iff there is a well-founded proof tree of x under \mathcal{R} .

Then $x \in \nu \widehat{\mathcal{R}}$ iff there is a proof tree of x under \mathcal{R} .

Plan

- 1 Motivation
- 2 Induction and Coinduction
 - Motivation
 - Theoretical Foundation
 - (Co)Inductive Sets Defined by Ground Inference Systems
- 3 Reachability Predicates
- 4 Logical Constrained Rewriting Systems (LCTRSs)
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- 6 Conclusion

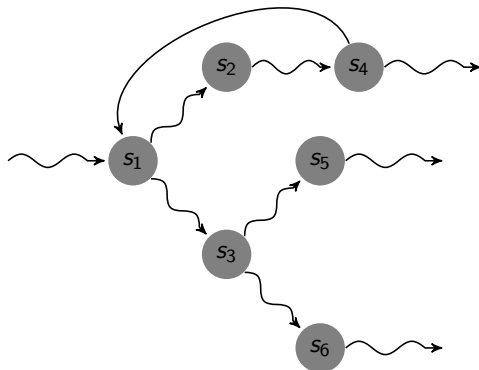
Overview

Semantics First! (J. Goguen)

- transition systems
- state predicate
- derivative (semantically)
- reachability predicate as pairs of state predicates

Transition Systems

(M, \rightsquigarrow) , with $\rightsquigarrow \subseteq M \times M$

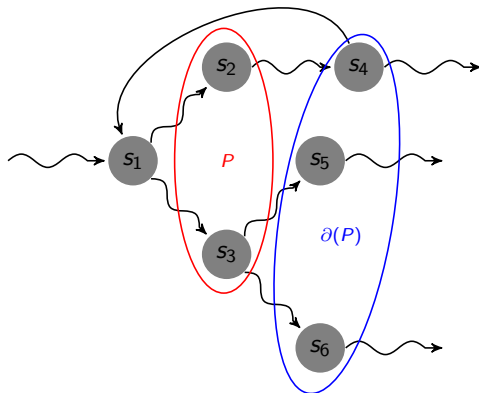


execution paths:

$$\frac{}{\gamma} \gamma \in M, \gamma \text{ irreducible} \quad \frac{\tau}{\gamma_0 \circ \tau} \gamma_0 \rightsquigarrow \text{hd}(\tau)$$

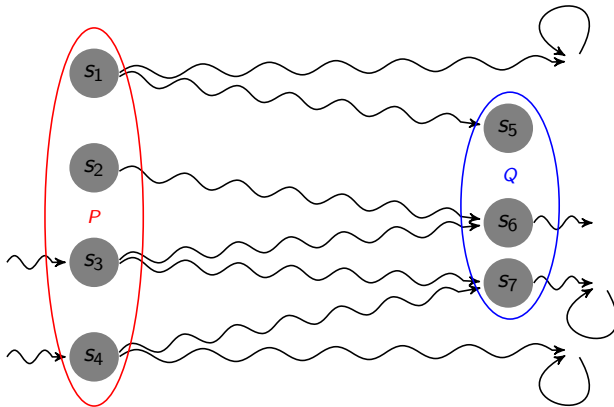
State Predicates and their Derivatives

- state predicate: $P \subseteq M$
- derivative of a state predicate P :
 $\partial(P) = \{\gamma' \mid \gamma \rightsquigarrow \gamma' \text{ for some } \gamma \in P\}$



Reachability Predicates

- a **reachability predicate** is a pair of state predicates: $P \Rightarrow Q$
- models: transition systems
- satisfiability: $(M, \rightsquigarrow) \models^{\forall} P \Rightarrow Q$ iff any execution path τ starting from P ($hd(\tau) \in P$) is infinite or eventually reaches Q



Satisfiability Coinductively

$$(M, \sim) \models^{\forall} P \Rightarrow Q$$

iff

$$P \Rightarrow Q \in \nu \widehat{\text{DVP}}$$

where DVP consists of the following rules:

$$\llbracket \text{Subs} \rrbracket \frac{}{P \Rightarrow Q} P \subseteq Q \quad \llbracket \text{Step} \rrbracket \frac{\partial(P \setminus Q) \Rightarrow Q}{P \Rightarrow Q} P \setminus Q \text{ runnable}$$

P is **runnable** if $P \neq \emptyset$ and for all $\gamma \in P$ there is $\gamma' \in M$ s.t. $\gamma \sim \gamma'$.

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Overview

(based on **IJCAR 2018** paper)

- builtin models (local computations, constraints over builtin model solvable by SMT)
- state predicates as constrained terms = $\langle \text{term} \mid \text{constraint-formulas} \rangle$
- reachability predicates as reachability formulas = pair of constrained terms
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Signatures Modulo a Builtin Model

- a **builtin model** M^b for a many-sorted **builtin signature** $\Sigma^b = (S^b, F^b)$.
Example: $S^b = \{Int, Bool\}$, $F^b = \{+, \times, \wedge, \vee, \dots\}$.
- an **order-sorted signature** (S, \leq, Σ) including Σ^b
- M^b is freely extended to a Σ -model M^Σ s. t.:
 - ▶ each $f \in \Sigma \setminus \Sigma^b$ is interpreted as a term constructor
 - ▶ the Σ^b -terms reduced to their values in M^b

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Constrained Terms

- **constrained terms** $\langle t \mid \phi \rangle$
 - ▶ t is a Σ -term
 - ▶ ϕ is a first-order (with equality) formula
- Example:
 $\langle \text{init}(n) \mid \exists u. 1 < u < n \wedge n \bmod u = 0 \rangle$
 $\text{init} \in \Sigma_{Int, Cfg}$, n and u variables of sort Int
- semantically, a constrained term defines a state predicate
 $\llbracket \langle t \mid \phi \rangle \rrbracket \triangleq \{ \alpha(t) \mid \alpha : X \rightarrow M^\Sigma \text{ s.t. } M^\Sigma, \alpha \models \phi \}.$

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Specification of Transition Systems as LCTRS

- LCTRS = Logical Constrained Term Rewriting System
- example:

$$\begin{aligned} \text{init}(n) &\rightarrow \text{loop}(n, 2) \text{ if } \top, \\ \text{loop}(i \times k, i) &\rightarrow \text{comp} \text{ if } k > 1, \\ \text{loop}(n, i) &\rightarrow \text{loop}(n, i + 1) \text{ if } \neg(\exists k. k > 1 \wedge n = i \times k). \end{aligned}$$

- the general form of a rule: $l \rightarrow r \text{ if } \phi$
- we may think that $\langle l \mid \phi \rangle$ and $\langle r \mid \phi \rangle$ are two constrained terms, but this is not entirely true (see the next slide)
- a LCTRS \mathcal{R} defines a transition relation $\sim_{\mathcal{R}}$ between the corresponding instances of l and r satisfying ϕ
example: $\text{loop}(5, 2) \sim_{\mathcal{R}} \text{loop}(5, 3)$, $\text{loop}(8, 2) \sim_{\mathcal{R}} \text{comp}$

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Reachability Properties of LCTRSs

- a reachability formula is a pair of constrained terms $\varphi \Rightarrow \varphi'$
- semantics:

$$\mathcal{R} \models^{\forall} \varphi \Rightarrow \varphi'$$

iff

$$(M^{\Sigma}, \sim_{\mathcal{R}}) \models^{\forall} \llbracket \sigma(\varphi) \rrbracket \Rightarrow \llbracket \sigma(\varphi') \rrbracket$$

for each $\sigma : \text{var}(\varphi) \cap \text{var}(\varphi') \rightarrow M^{\Sigma}$

- the shared variable must have the same values

Derivatives of Constrained Terms

- the derivatives of state predicates are extended to constrained terms
- the **set of derivatives** of a constrained term $\varphi \triangleq \langle t \mid \phi \rangle$ w.r.t. a rule $l \rightarrow r$ if ϕ_{lr} is

$$\Delta_{l,r,\phi_{lr}}(\varphi) \triangleq \{ \langle c[r] \mid \phi' \rangle \mid \phi' \triangleq \phi \wedge t = c[l] \wedge \phi_{lr}, \\ c[\cdot] \text{ an appropriate context} \\ \phi' \text{ is satisfiable} \}.$$

- example:

$$\Delta_{\mathcal{R}}(\langle \text{init}(n) \mid \exists u. 1 < u < n \wedge n \bmod u = 0 \rangle) = \\ \{ \langle \text{loop}(n, 2) \mid \exists u. 1 < u < n \wedge n \bmod u = 0 \rangle \}.$$

Symbolic Derivatives and the Concrete Ones Agree

Theorem

Let $\varphi \triangleq \langle t \mid \phi \rangle$ be a constrained term, \mathcal{R} a constrained rule system, and $(M^\Sigma, \sim_{\mathcal{R}})$ the transition system defined by \mathcal{R} . Then $\llbracket \Delta_{\mathcal{R}}(\varphi) \rrbracket = \partial(\llbracket \varphi \rrbracket)$.

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Overview

- lift up the inference system to reachability formulas
- add a circular inference rule to infinite proof trees into finite ones

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Proof System (DSTEP(\mathcal{R}))

it corresponds to the semantic coinductive definition

$$\text{[axiom]} \frac{}{\langle t_l \mid \perp \rangle \Rightarrow \langle t_r \mid \phi_r \rangle}$$

$$\text{[subs]} \frac{\langle t_l \mid \phi_l \wedge \neg(\exists \tilde{x}. t_l = t_r \wedge \phi_r) \rangle \Rightarrow \langle t_r \mid \phi_r \rangle}{\langle t_l \mid \phi_l \rangle \Rightarrow \langle t_r \mid \phi_r \rangle} \text{cond}_s$$

$$\text{[der}^\forall] \frac{\langle t^j \mid \phi^j \rangle \Rightarrow \langle t_r \mid \phi_r \rangle, j \in \{1, \dots, n\}}{\langle t_l \mid \phi_l \rangle \Rightarrow \langle t_r \mid \phi_r \rangle} \text{cond}_d$$

$$\text{where } \Delta_{\mathcal{R}}(\langle t_l \mid \phi_l \rangle) = \{\langle t^1 \mid \phi^1 \rangle, \dots, \langle t^n \mid \phi^n \rangle\}$$

The conditions ensure the sound application of the rules.

Example

The **infinite proof tree** for the reachability formula $\langle \text{init}(n) \mid \psi \rangle \Rightarrow \varphi_r$, where $\psi \triangleq \exists u. 1 < u < n \wedge n \bmod u = 0$ and $\varphi_r \triangleq \langle \text{comp} \mid \top \rangle$:

$$\frac{\frac{\frac{}{\langle \text{comp} \mid \perp \rangle \Rightarrow \varphi_r} \text{[axiom]}}{\langle \text{comp} \mid \psi \wedge \phi_a \rangle \Rightarrow \varphi_r} \text{[subs]} \quad \frac{\frac{\frac{}{\langle \text{comp} \mid \perp \rangle \Rightarrow \varphi_r} \text{[axiom]}}{\langle \text{comp} \mid \psi \wedge \phi_2 \wedge \phi_b \rangle \Rightarrow \varphi_r} \text{[subs]} \quad \vdots}{\langle \text{loop}(n, 3) \mid \psi \wedge \phi_2 \rangle \Rightarrow \varphi_r} \text{[der}^\forall]}{\langle \text{loop}(n, 2) \mid \psi \rangle \Rightarrow \varphi_r} \text{[der}^\forall]}{\langle \text{init}(n) \mid \psi \rangle \Rightarrow \varphi_r} \text{[der}^\forall]}$$

Infinite proof trees cannot be handled in practice, therefore we look for finite representations of them.

Extending the Proof System to the Unbounded Case

Let G be a finite set reachability formulas (goals that we intend to prove). Then the set of rules $\text{DCC}(\mathcal{R}, G)$ consists of $\text{DSTEP}(\mathcal{R})$, together with

$$[\text{circ}] \frac{\langle t_r^c \mid \phi_l \wedge \phi \wedge \phi_r^c \rangle \Rightarrow \varphi_r, \quad \langle t_l \mid \phi_l \wedge \neg\phi \rangle \Rightarrow \varphi_r}{\langle t_l \mid \phi_l \rangle \Rightarrow \varphi_r} \quad \begin{array}{l} \phi \text{ is } \exists \text{var}(t_l^c, \phi_l^c). t_l = t_l^c \wedge \phi_l^c, \\ \langle t_l^c \mid \phi_l^c \rangle \Rightarrow \langle t_r^c \mid \phi_r^c \rangle \in G. \end{array}$$

Theorem (Circularity Principle)

Let \mathcal{R} be a constrained rule system and G a set of goals. If $(\mathcal{R}, G) \vdash^\forall G$ then $\mathcal{R} \models^\forall G$.

Example

In order to prove $\langle \text{init}(n) \mid \psi \rangle \Rightarrow \langle \text{comp} \mid \top \rangle$, we choose the following set of circularities

$$G = \left\{ \begin{array}{l} \langle \text{init}(n) \mid \psi \rangle \Rightarrow \langle \text{comp} \mid \top \rangle, \\ \langle \text{loop}(n, i) \mid 2 \leq i \wedge \exists u. i \leq u < n \wedge n \bmod u = 0 \rangle \Rightarrow \langle \text{comp} \mid \top \rangle \end{array} \right\}.$$

The **finite proof tree** for the first circularity:

$$\frac{\frac{\frac{}{\langle \text{comp} \mid \perp \rangle \Rightarrow \varphi_r} \text{[axiom]}}{\langle \text{comp} \mid \psi \wedge \phi \wedge \top \rangle \Rightarrow \varphi_r} \text{[subs]} \quad \frac{}{\langle \text{loop}(n, 2) \mid \psi \wedge \neg \phi \rangle \Rightarrow \varphi_r} \text{[axiom]}}{\frac{\langle \text{loop}(n, 2) \mid \psi \rangle \Rightarrow \varphi_r}{\langle \text{init}(n) \mid \psi \rangle \Rightarrow \varphi_r} \text{[der}^\forall\text{]}} \text{[circ]}$$

Example

In order to prove $\langle \text{init}(n) \mid \psi \rangle \Rightarrow \langle \text{comp} \mid \top \rangle$, we choose the following set of circularities

$$G = \left\{ \begin{array}{l} \langle \text{init}(n) \mid \psi \rangle \Rightarrow \langle \text{comp} \mid \top \rangle, \\ \langle \text{loop}(n, i) \mid 2 \leq i \wedge \exists u. i \leq u < n \wedge n \bmod u = 0 \rangle \Rightarrow \langle \text{comp} \mid \top \rangle \end{array} \right\}.$$

The **finite proof tree** for the first circularity:

$$\frac{\frac{\frac{}{\langle \text{comp} \mid \perp \rangle \Rightarrow \varphi_r} \text{[axiom]}}{\langle \text{comp} \mid \psi \wedge \phi \wedge \top \rangle \Rightarrow \varphi_r} \text{[subs]} \quad \frac{}{\langle \text{loop}(n, 2) \mid \psi \wedge \neg \phi \rangle \Rightarrow \varphi_r} \text{[axiom]}}{\frac{\langle \text{loop}(n, 2) \mid \psi \rangle \Rightarrow \varphi_r}{\langle \text{init}(n) \mid \psi \rangle \Rightarrow \varphi_r} \text{[der}^\forall\text{]}} \text{[circ]}$$

Example Proof Tree for the Second Circularity

$$\frac{\frac{\langle c \mid \perp \rangle \Rightarrow \varphi_r}{\langle c \mid \psi_i \wedge \psi_a \rangle \Rightarrow \varphi_r} \quad \frac{\frac{\langle c \mid \perp \rangle \Rightarrow \varphi_r}{\langle c \mid \psi_i \wedge \psi_b \wedge \psi_c \rangle \Rightarrow \varphi_r} \quad \frac{\langle l(n, i+1) \mid \psi_i \wedge \psi_b \wedge \neg \psi_c \rangle \Rightarrow \varphi_r}{\langle l(n, i+1) \mid \psi_i \wedge \psi_b \rangle \Rightarrow \varphi_r}}{\langle l(n, i) \mid \psi_i \rangle \Rightarrow \langle c \mid \top \rangle} \text{ [der}^\forall\text{]}$$

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Conclusion

- we defined a framework for proving reachability properties consisting of
 - ▶ logical constrained rewriting systems, for specifying transition systems (LCTRS)
 - ▶ a coinductive proof system consisting of four rules
- LCTRSs are expressive enough to describe semantics of programming languages (K Framework, G. Roşu)
- there is a prototype that implements the proof system (Ciobâcă, Buruiană)
- further work includes
 - ▶ unification modulo builtins (a first step in WOLLIC 2018)
 - ▶ extension of the proof systems to program equivalence (a first step in FAoC 2015)